| CS 6505 : Computability and Algorithms | Spring 2014 |
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| Traveling Salesman Problem |  |
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## 1 Traveling Salesman Problem

- $G=(V, E)$ is a complete undirected graph
- Non-negative integer $\operatorname{cost} c(u, v)$ with each edge $(u, v) \in E$.
- TSP: Find a Hamiltonian cycle of $G$ with minimum cost.
- TSP with triangle inequality: The cost function $c$ satisfies the triangle inequality if for all vertices $u, v, w \in V$ :

$$
c(u, w) \leq c(u, v)+c(v, w) .
$$

- TSP with triangle inequality is NP-Complete: also known as metric TSP or constrained TSP. [Proved in HW]
- The TSP has several applications in planning, logistics, VLSI design, DNA sequencing etc.
- Probably the most well-studied problem in combinatorial optimization.


## 2 Inapproximability of TSP

Claim: If $P \neq \mathrm{NP}$, then for any polynomial time computable function $\rho(n)$, there is no polynomial time $\rho(n)$-approximation algorithm. for the general TSP.

- Suppose that there is a polynomial time $\rho$ approximation algorithm, say $\mathcal{A}$ for TSP.
- We will show that we can use $\mathcal{A}$ to decide the Hamiltonian Cycle problem is which is NP-complete thus showing that $\mathrm{P}=\mathrm{NP}$.
- Let $G=(V, E)$ be an undirected graph.
- Construct a complete graph $G^{\prime}=\left(V, E^{\prime}\right)$ from $V$.
- For each $u, v \in E^{\prime}$, assign an integer cost:
$* c(u, v)=1$ if $(u, v) \in E$ and
* $c(u, v)=\rho \times|V|+1$ if $(u, v) \notin E$.
- $\operatorname{Run} \mathcal{A}$ on $G^{\prime}$ with this cost function on the edges.
- Suppose $G$ has a Hamiltonian cycle.
* The cost of this cycle in $G^{\prime}$ is $|V|$.
* $\mathcal{A}$ returns a tour whose cost is at most $\rho \times|V|$.
- Suppose $G$ has no Hamiltonian cycle.
* The cost of any Hamiltonian cycle in $G^{\prime}$ is $>\rho \times|V|$ :
- Any Hamiltonian cycle in $G^{\prime}$ must include an edge not in $E$.
- Any Hamiltonian cycle has cost at least $(\rho \times|V|+1)+(|V|-1)$ which is $>\rho \times|V|$.


## 3 A 2- approximation algorithm for metric TSP

1. Construct a minimum spanning tree (MST) $T$.
2. Double every edge of $T$ to get an Eulerian graph.
3. Find an Eulerian tour $W$ on this graph. We can take a preorder traversal of $T$.
4. Let $L$ be the list of vertices obtained by deleting all duplicates in $W$ by keeping, for all vertices $u$, only the first visit to the vertex $u$.
5. Let $H$ be the cycle corresponding to this traversal.

## 4 Analysis

Claim: The algorithm given above is a 2-optimal approximation algorithm.

- Let $H^{*}$ be an optimal TSP tour.
- Then, $C(T) \leq C\left(H^{*}\right)$.
- Deleting an edge from $H^{*}$ gives a spanning tree of $G$.
- Let $W$ be a list of vertices from a preorder traversal of $T$ before removing duplicates.
- Then, $C(W)=2 C(T)$ :
- Every edge of $T$ is traversed exactly twice in $W$.
- Therefore, $C(W) \leq 2 C\left(H^{*}\right)$.
- Let $H$ be the cycle obtained by deleting all duplicates in $W$ by keeping, for all vertices $u$, only the first visit to the vertex $u$.
- Then, $C(L) \leq C(W)$ :
- Let $W^{\prime}$ be the list obtained from $W$ after the deletion of some vertices.
- Say a vertex $v$ occurring in the order $u, v, w$ in $W^{\prime}$ is deleted.
- Then, the cost of the resulting list is at most the cost of $W^{\prime}$ :
* There is an edge between $u$ and $w$ since $G$ is complete.
* By triangle inequality, $c(u, w) \leq c(u, v)+c(v, w)$.
- Exercise: The analysis is tight!


## 5 Christofides Algorithm: 3/2 approximation for metric TSP

1. Construct a minimum spanning tree $T$.
2. Compute a minimum cost perfect matching $M$ on the set of odd-degree vertices of $T$. Add $M$ to obtain an Eulerian graph.
3. Find an Eulerian tour $W$ on this graph.
4. Let $L$ be the list of vertices obtained by deleting all duplicates in $W$ by keeping, for all vertices $u$, only the first visit to the vertex $u$.
5. Let $H$ be the cycle corresponding to this traversal.

## 6 Analysis

- Key idea: Use perfect matching in odd degree vertices of MST to obtain an Eulerian graph in step 2.
- Let $S \subseteq V$ and $|S|$ is even and $M$ is a minimum cost perfect matching on $S$ then $\operatorname{cost}(M) \leq \mathrm{Opt} / 2$
- Let $H^{*}$ be the optimal TSP tour and $\operatorname{cost}\left(H^{*}\right)=\mathrm{Opt}$
- Let $H^{\prime}$ be the tour on $S$ by short-cutting $H^{*}$.
- By triangle inequality, $\operatorname{cost}\left(H^{\prime}\right) \leq$ Opt.
- Now $H^{\prime}$ is union of two perfect matchings on $S$.
- The cheaper of these two matchings has cost $\leq \operatorname{cost}\left(H^{\prime}\right) / 2 \leq \mathrm{Opt} / 2$.
- $\operatorname{cost}(H) \leq \operatorname{cost}(T)+\operatorname{cost}(M) \leq \mathrm{Opt}+\mathrm{Opt} / 2 \leq 3 / 2 \mathrm{Opt}$.
- The Analysis is tight!
- Exercise: Find such a tight example.


## 7 Other Comments:

- It is a BIG open question in theoretical computer science to get a $3 / 2-\epsilon$ approximation for metric TSP for any $\epsilon>0$.
- The Euclidean TSP, or planar TSP, is the TSP with the distance being the ordinary Euclidean distance.
- The Euclidean TSP is a particular case of the metric TSP, since distances in a plane obey the triangle inequality.
- Sanjeev Arora and Joseph S. B. Mitchell were awarded the Gödel Prize in 2010 for their concurrent discovery of a PTAS for the Euclidean TSP.
- There are commercial softwares like Concorde which can solve most of the problems with millions of cities within a small fraction of $1 \%$ of the optimal.


## 8 Resources:

I am following chapter 2.4 (The traveling salesman problem) of 1 for the lectures. The book is freely available online: http://www.designofapproxalgs.com/. You can also see chapter 3 (Steiner Tree and TSP) from 2.

## References

[1] Williamson, David P and Shmoys, David B. The Design of Approximation Algorithms. Cambridge University Press 2011.
[2] Vazirani, Vijay V. Approximation Algorithms. Springer 2001.

